

Practical Approach to Evacuation Planning Via Network Flow and Deep Learning

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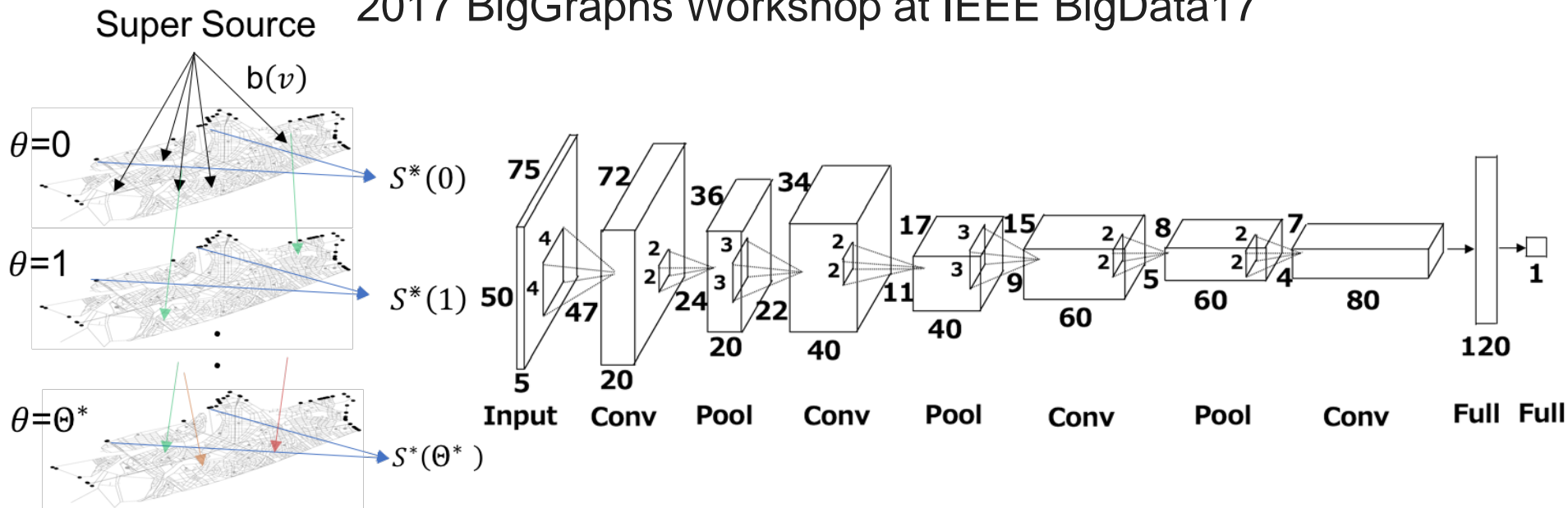
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Evacuation Map

Yodogawa Area in Osaka City

#nodes : 2,933

#edges : 8,924

#evacuees : 50,000 ~ 80,000

#shelters

← Based on
midnight population

with finite capacity : 36 (total volume:35,549)

with infinite capacity : 50 (each volume:∞)

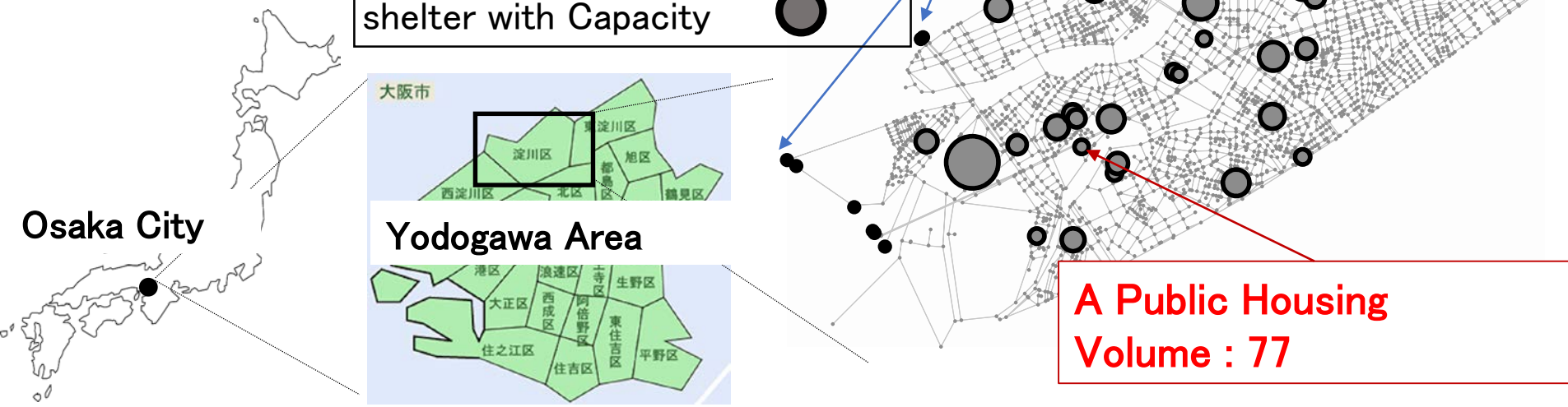
Higher Grounds

Tall and Strong Buildings

Higher Grounds
Volume: ∞

shelter without Capacity
shelter with Capacity

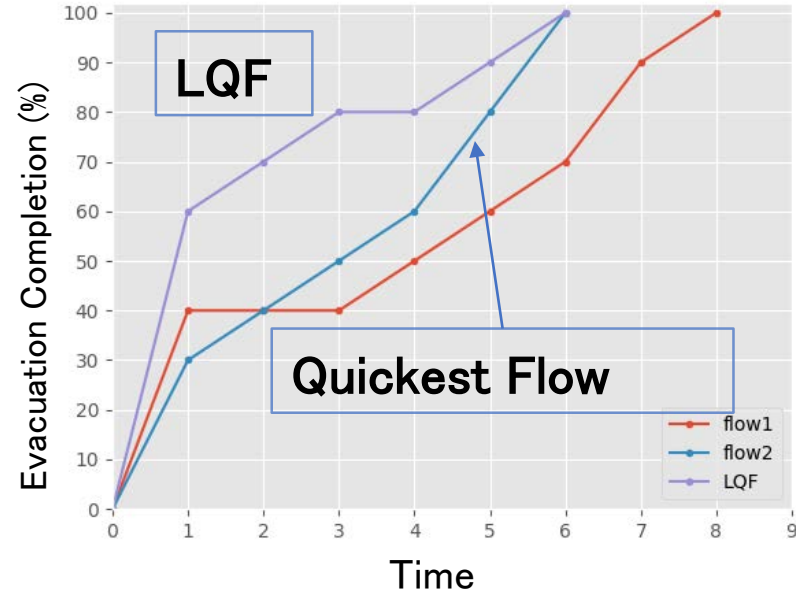
A Public Housing
Volume : 77



Lexicographically Quickest Flow(LQF)

Definition

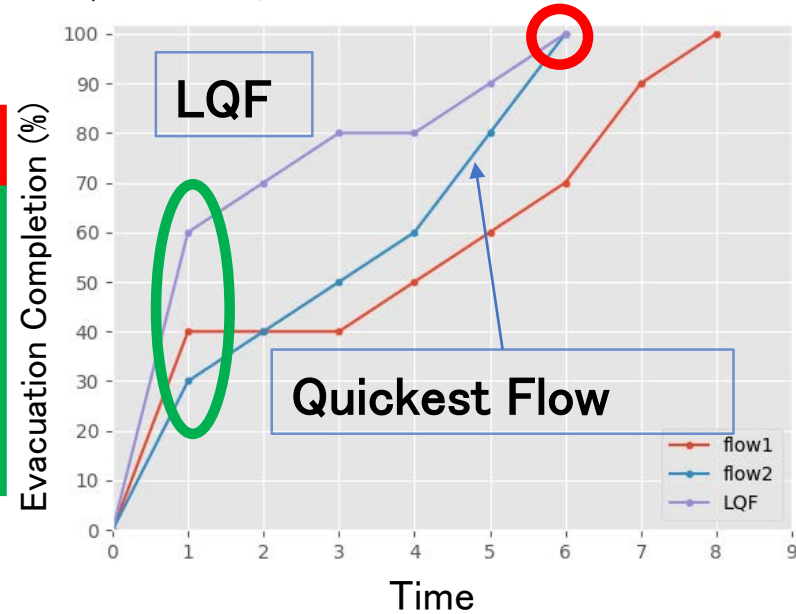
- Minimizes the evacuation time Θ^*
- Greedily maximize the cumulative number of evacuees who have already completed evacuation at every time θ in the order of $\theta = 1, 2, \dots, \Theta^*$



Lexicographically Quickest Flow(LQF)

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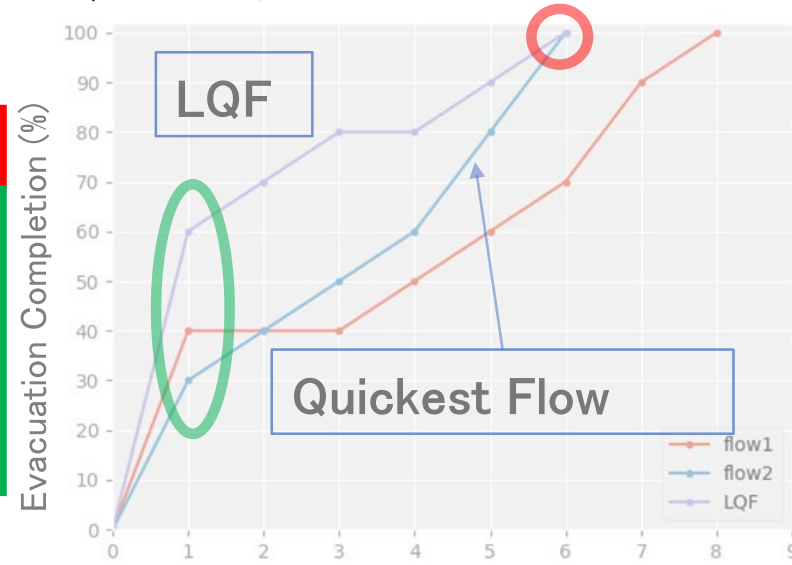
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Lexicographically Quickest Flow(LQF)

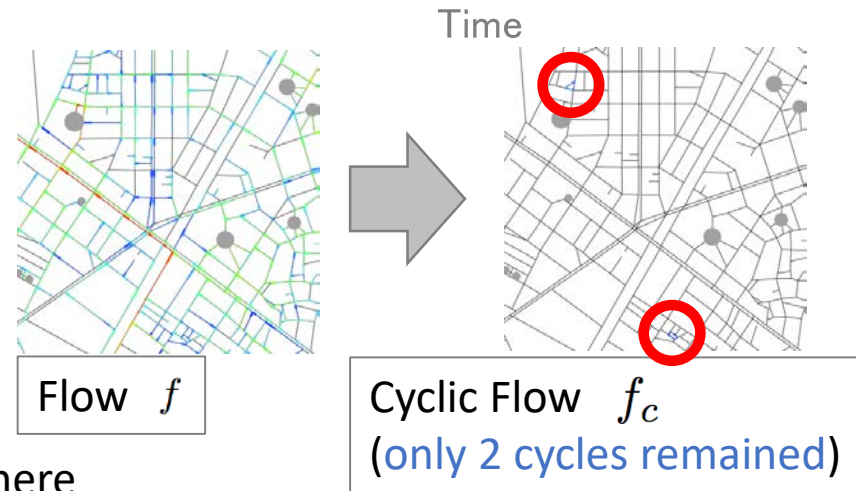
Definition

- Minimizes the evacuation time Θ^*
- Greedy maximize the cumulative number of evacuees who have already completed evacuation at every time θ in the order of $\theta = 1, 2, \dots, \Theta^*$



Practical Property

- The LQF also has a high efficiency with respect to **total pedestrian flow** of all evacuees to the refuges
- To check this property, we decomposed the LQF into cyclic flow and cycle-free flow by solving the QP below:



minimize $\sum_{e \in A} (f(e) - f_c(e))^2$

subject to $f_c \in \mathcal{F}_c$

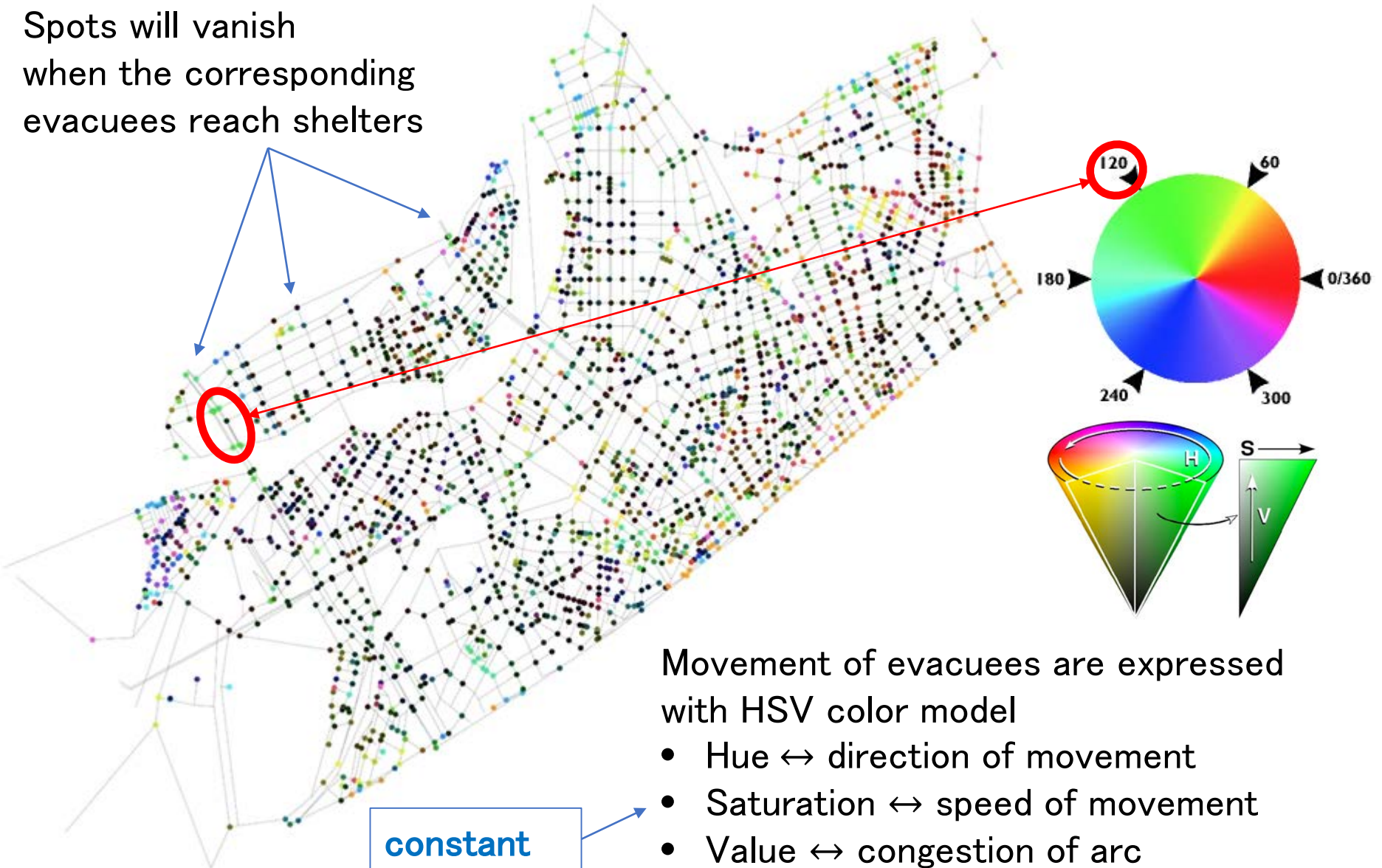
$0 \leq f_c(e) \leq f(e) \quad (\forall e \in A \text{ s.t. } f(e) \geq 0)$

$f(e) \leq f_c(e) \leq 0 \quad (\forall e \in A \text{ s.t. } f(e) \leq 0)$

- where
- $f(e)$ is the total refugees that passed the arc e
 - A : the set of arcs
 - $\mathcal{F}_c := \{f : A \rightarrow \mathbb{R} \mid f \text{ is a cyclic flow}\}$

Visualization of LQF

Spots will vanish
when the corresponding
evacuees reach shelters



Movement of evacuees are expressed
with HSV color model

- Hue ↔ direction of movement
- Saturation ↔ speed of movement
- Value ↔ congestion of arc

Lexicographically Quickest Flow (LQF)

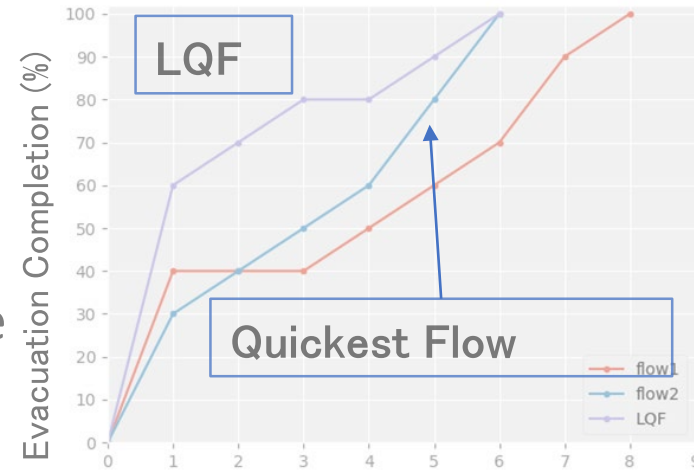
Pros(practical property)

- Minimizes the evacuation time Θ^*
- Greedily maximize the cumulative number of evacuees
→ More people reach shelters in the early stage
- There are few unnecessary movements

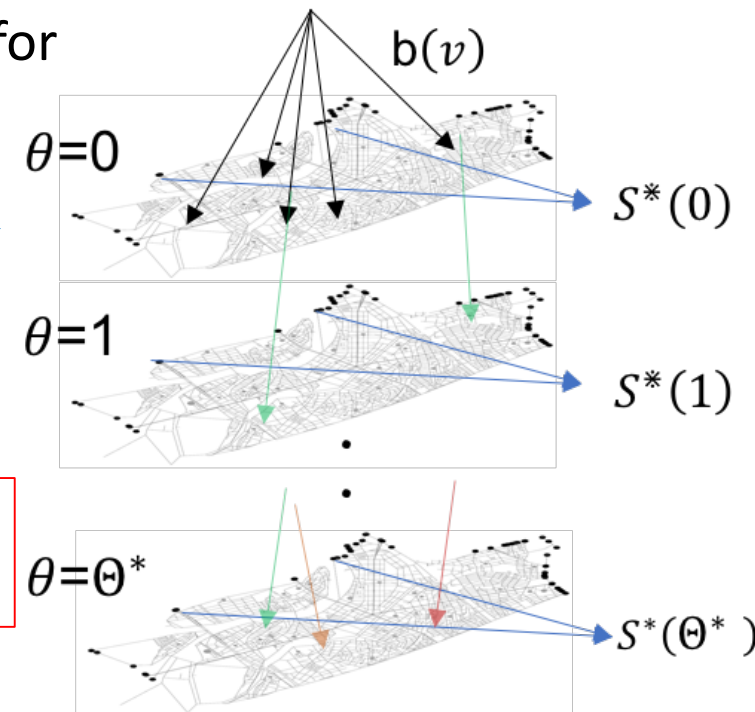
Cons

- **Not practical**(7h for the target area)
 - Compute the maximum flow repeatedly for the time-expanded graph.
 - Size of time-expanded graph is huge

	Original	Time-Expanded($\theta = 2,824$)
#nodes	2,933	8,300,000
#edges	8,924	32,800,000



Super Source



➔ To utilize practical property of LQF, we combine it with Deep Learning

Normal Time

Population
Distribution



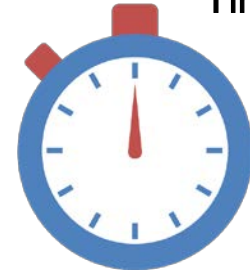
LQF



Movements of
Each Evacuee



Evacuation
Completion
Time(ECT)



Normal Time

Population Distribution



LQF



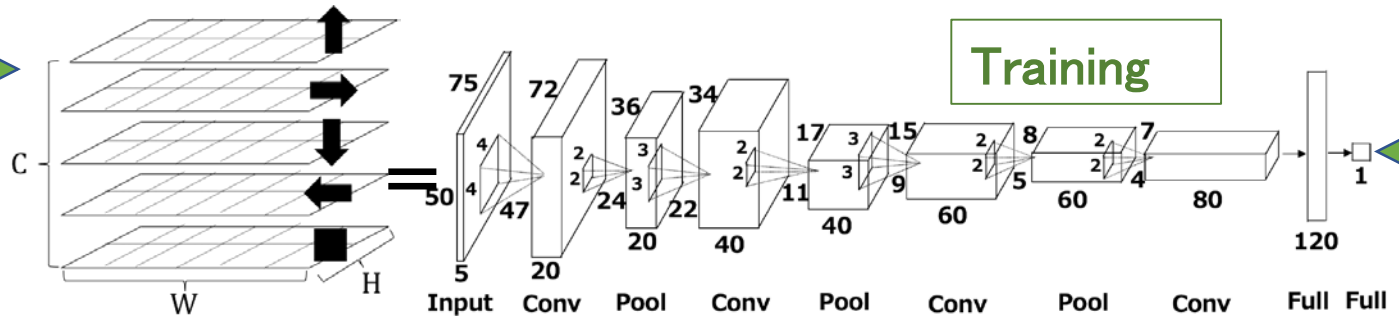
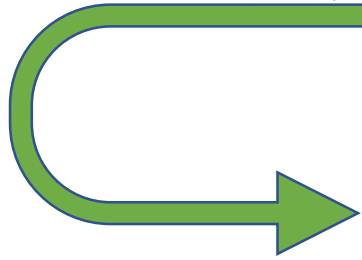
Movements of Each Evacuee



Evacuation Completion Time(ECT)



Preprocessing Techniques



Normal Time

Population Distribution



Movements of Each Evacuee



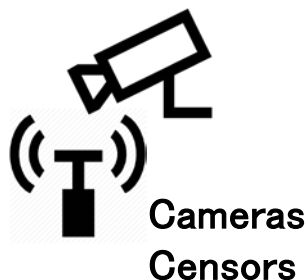
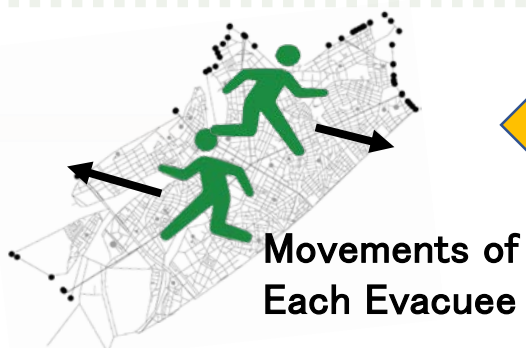
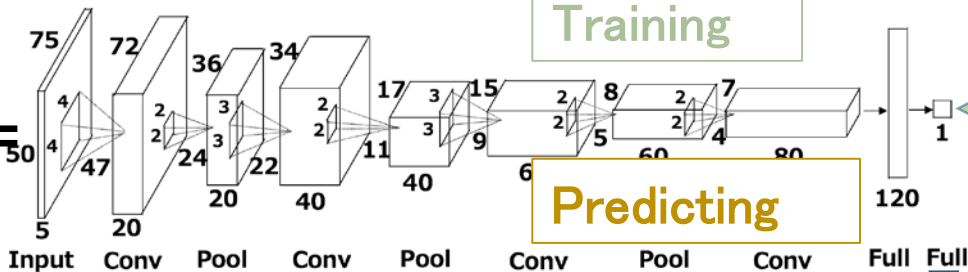
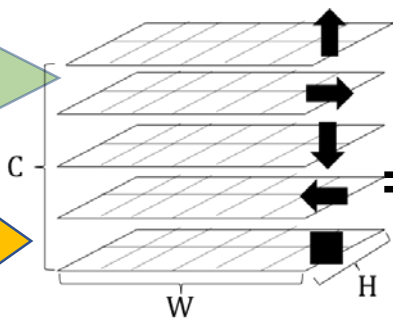
Evacuation Completion Time(ECT)



LQF



Preprocessing Techniques



Evacuation Completion Time(ECT)



Emergency

Normal Time

Population Distribution

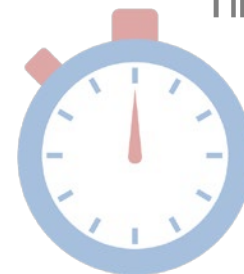


Movements of Each Evacuee

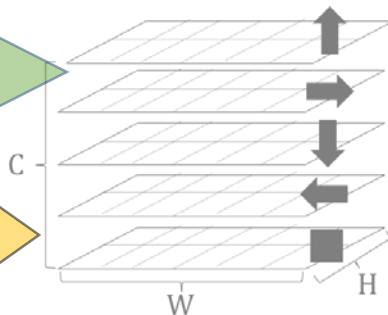


LQF

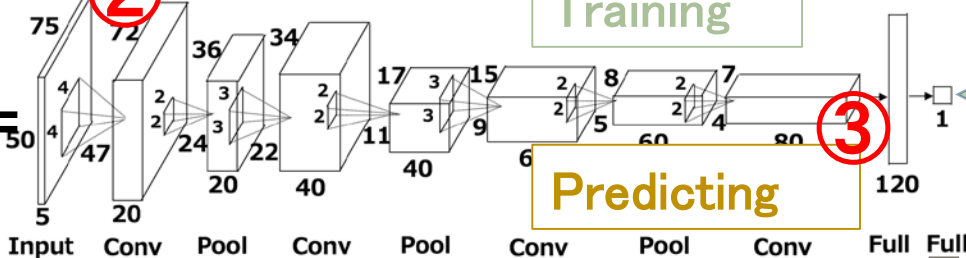
Evacuation Completion Time(ECT)



1 Preprocessing Techniques



2

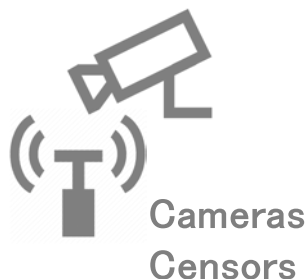
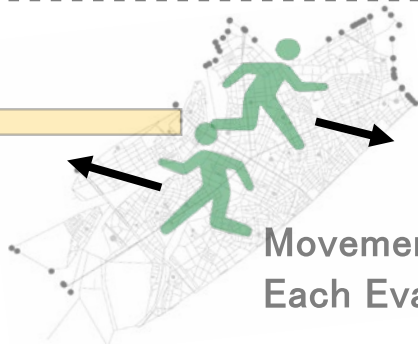


Training

Predicting

3

Movements of Each Evacuee



Evacuation Completion Time(ECT)



Emergency

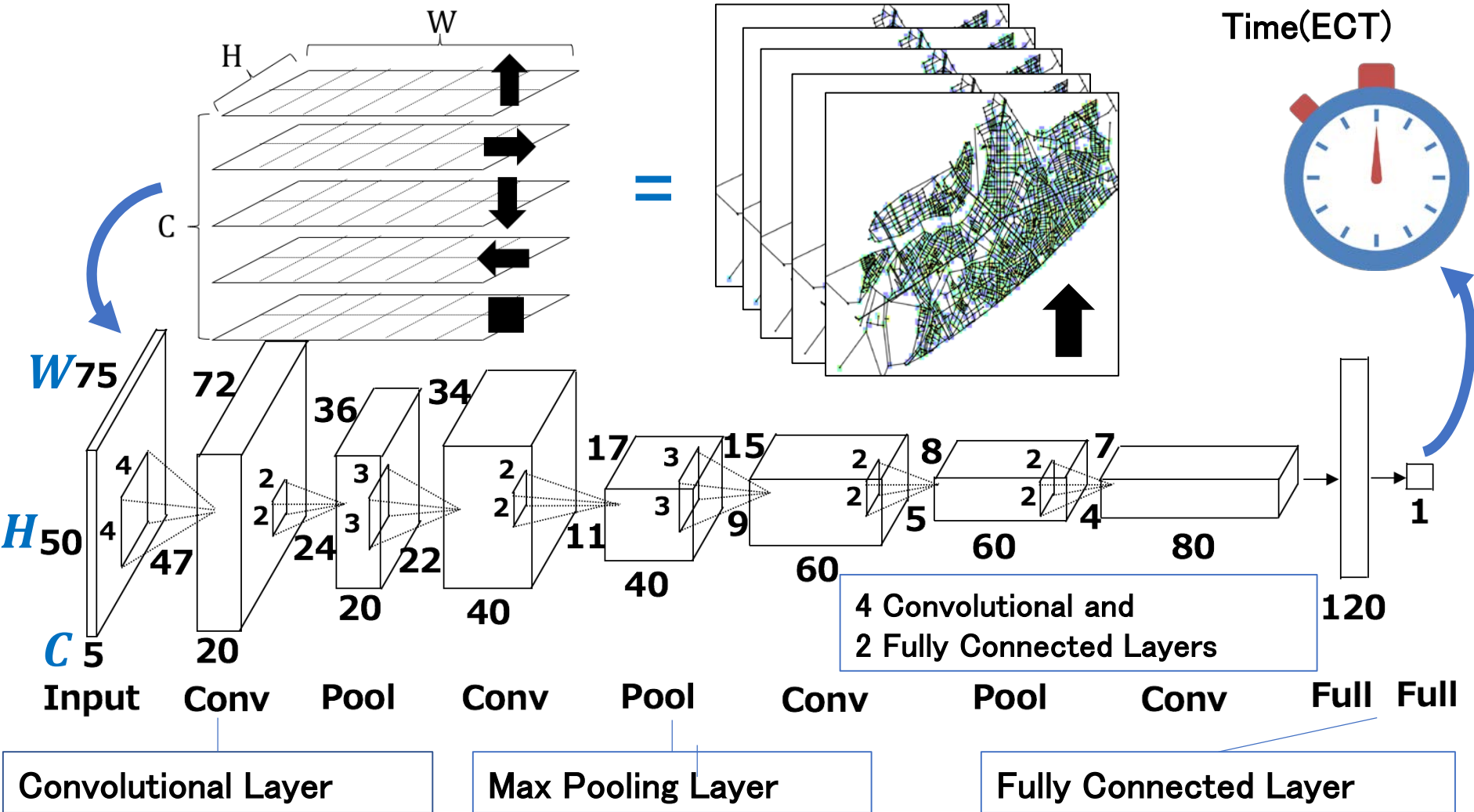
Convolutional Neural Network(CNN)

Input

The number of evacuees moving in specific direction/pausing

Output

Evacuation Completion Time(ECT)

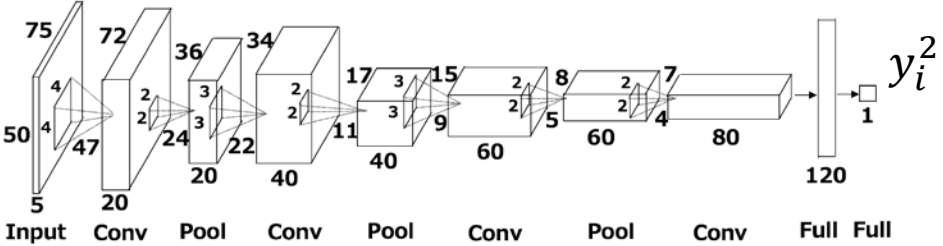


Optimizer and Output of CNN

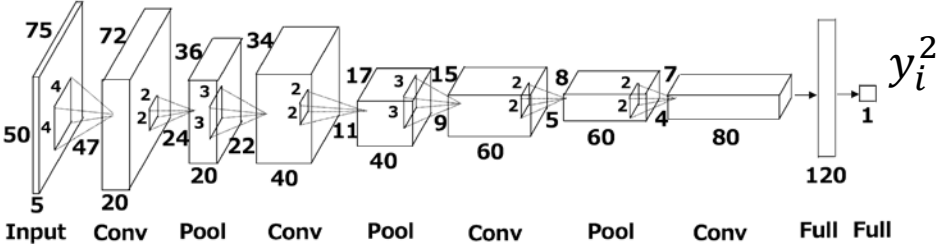
Euclidean Loss (cost function)

$$\frac{1}{2N} \sum_{i=1}^N \|y_i^1 - y_i^2\|^2$$

y_i^1 : Accuare output(LQF_T)
 y_i^2 : Predicting output
 N : data size



Optimizer and Output of CNN



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Adam(optimizer)

- First-order gradient-based optimization
 - feasible to compute in practice for high-dimensional data
- Storing exponentially decaying average of past gradient and squared gradient
 - Large updates for infrequent and smaller updates for frequent
 - accelerate learning

Optimizer and Output of CNN

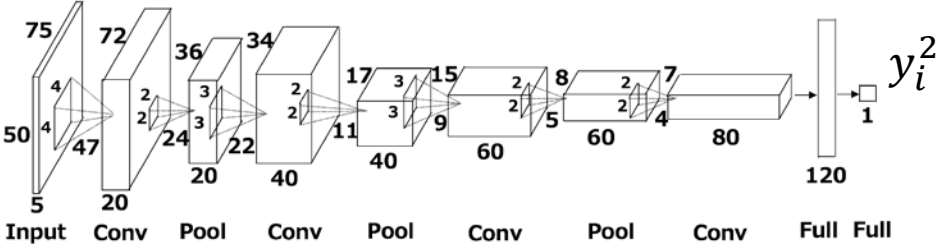
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<p>Accurate =2,716</p>	<p>Accurate =2,000</p>
<p>Predicting:2636 Error:80(2.9%)</p>	<p>Predicting:2036 Error:36(1.3%)</p>
<p>Accurate =1,700</p>	<p>Accurate =1,000</p>
<p>Predicting:1741 Error:41(1.5%)</p>	<p>Predicting:1038 Error:38(1.4%)</p>

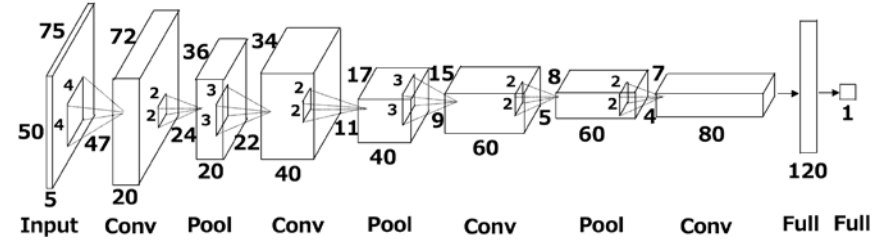
Error := |Accurate - Predicting| (Error / 2,751)
 Note: 2,751 is the average evacuation time

Results of Our Model

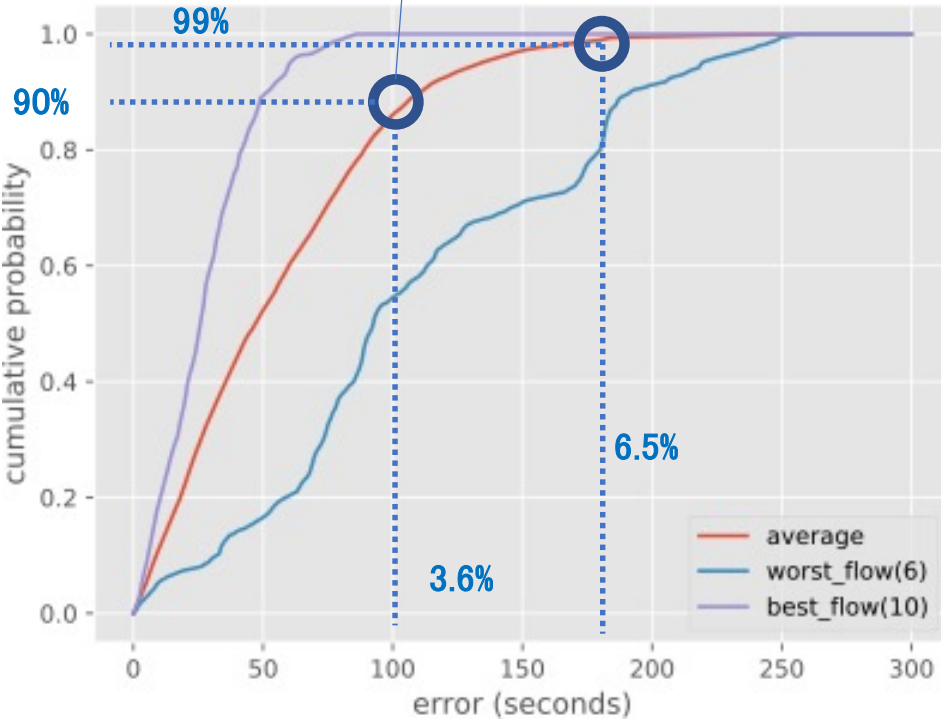
Data

#Training Data: 43,200

#Test Data: 5,400



90% probability that we make prediction within 3.6% error



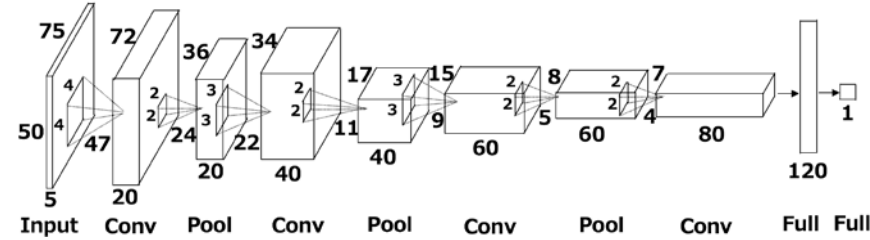
Cumulative Probabilities

Results of Our Model

Data

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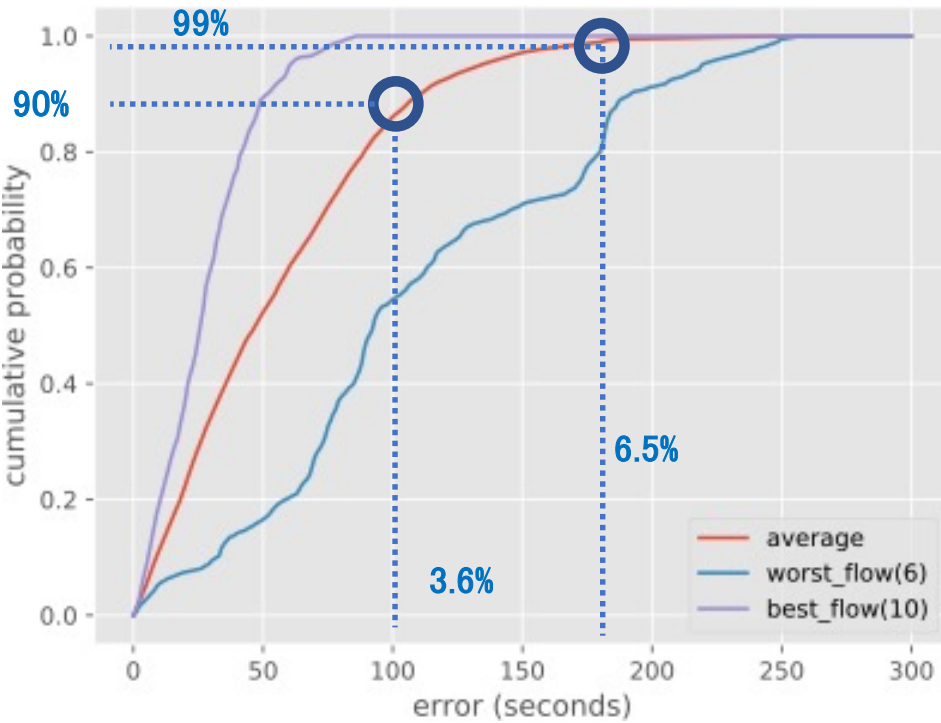
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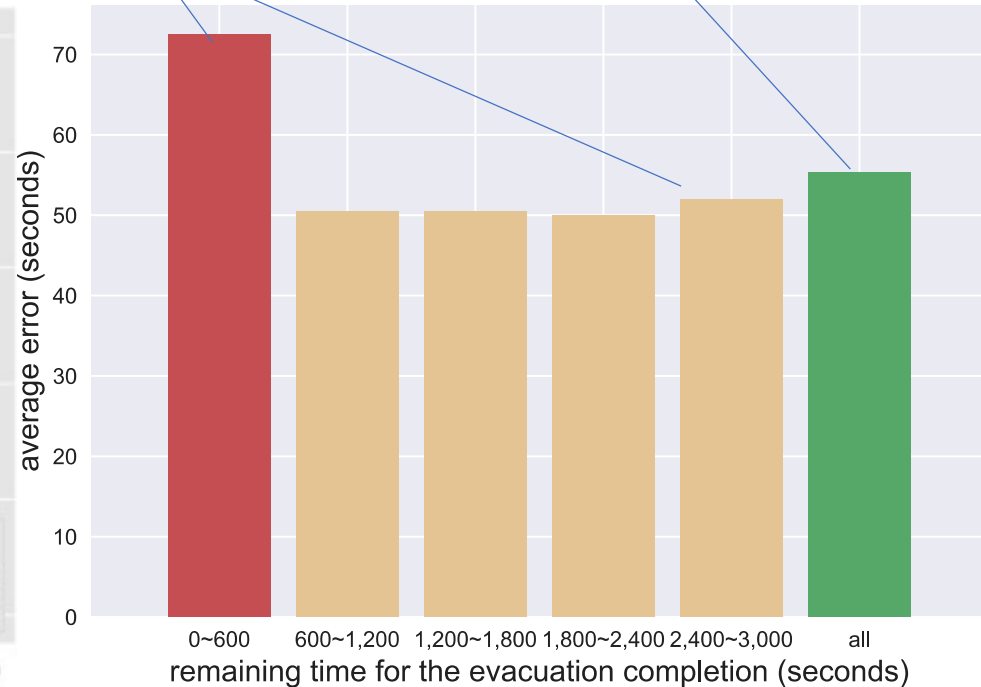
90% probability that we make prediction within 3.6% error

Average error(55s 2%) is quite a small

Prediction for the early stage is better than that for the final stage



Cumulative Probabilities



Average Error in Several Stages of Evacuation

Summary

Previous Model(LQF)

Not practical(7h)

- Compute max-flow repeatedly for time-expanded graph
- Time-expanded graph is huge



Proposed Model

Practical (less than 1s)

- Combing LQF and CNN
- Predict evacuation completion time immediately(less than 1s) and almost accurately(2%)

